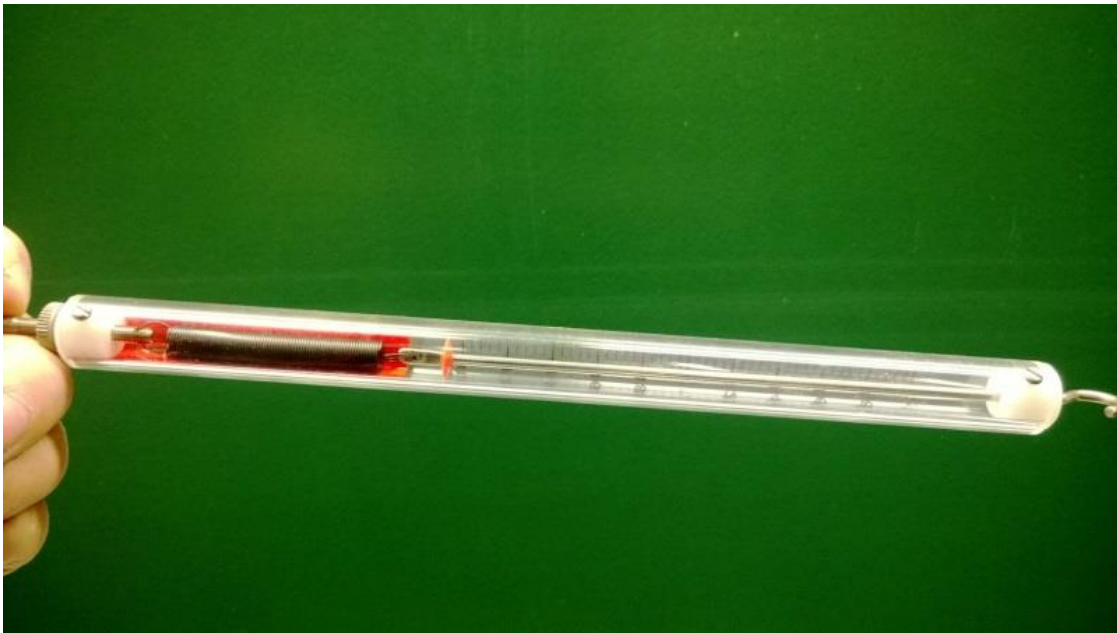


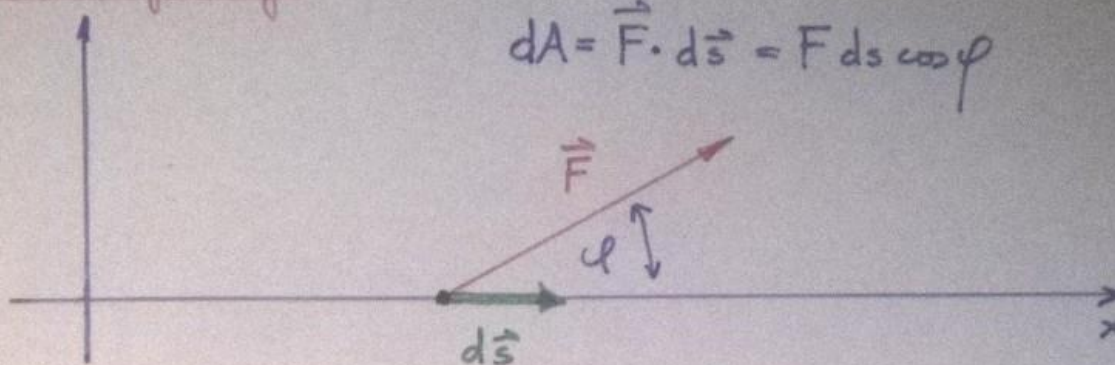
# KINETIČNA ENERGIJA

Delo



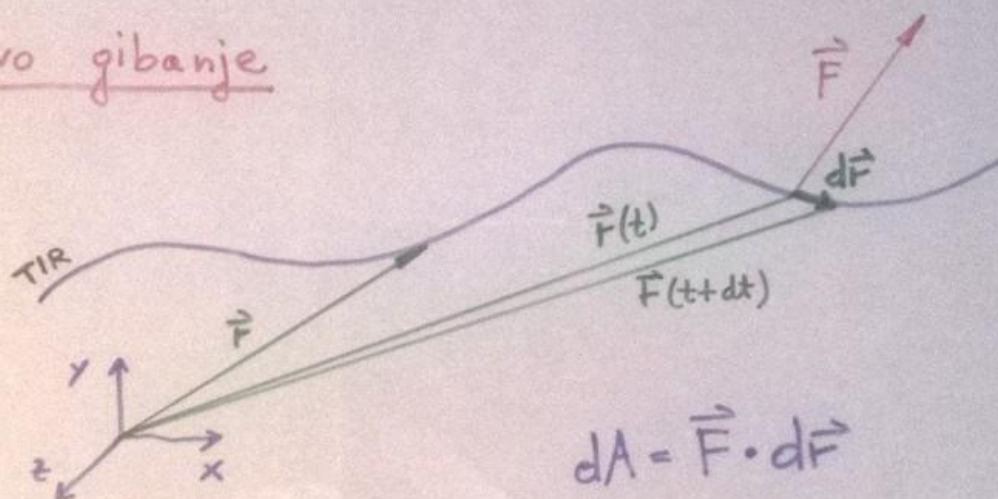
## Delo (za točkasto telo)

- premo gibanje



$$dA = \vec{F} \cdot d\vec{s} = F ds \cos \varphi$$

- krivo gibanje



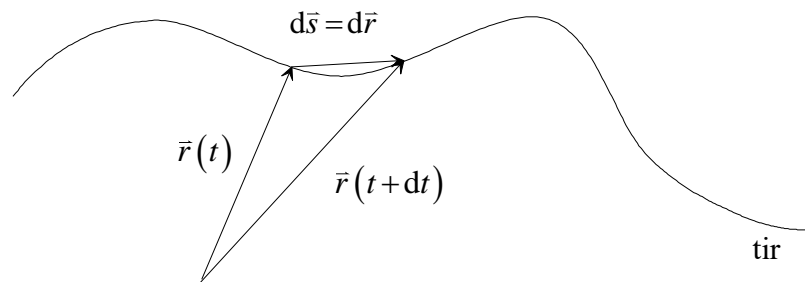
$$dA = \vec{F} \cdot d\vec{F}$$

enota za delo:  $1 \text{ Nm} \equiv 1 \text{ J}$  (joule)

## Točkasto telo – kinetična energija

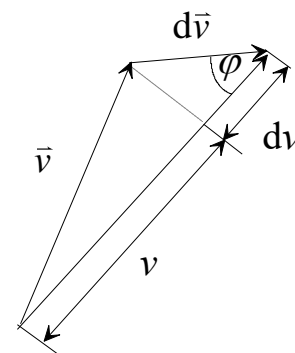
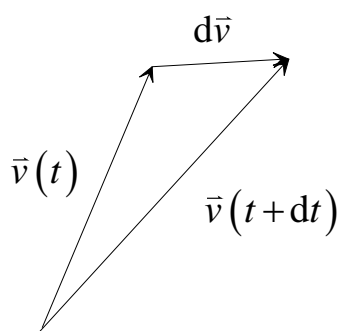
delo rezultante zunanjih sil ( $\vec{F}$ ) na točkasti maso  $m$

$$A = \int \vec{F} \cdot d\vec{s} = \int \vec{F} \cdot d\vec{r} \quad \vec{F} = m\vec{a} = m \frac{d\vec{v}}{dt}$$



$$d\vec{r} = \vec{v} dt$$

$$A = \int \vec{F} \cdot d\vec{r} = \int m \frac{d\vec{v}}{dt} \cdot d\vec{r} = \int m \frac{d\vec{v}}{dt} \cdot \vec{v} dt = \int m d\vec{v} \cdot \vec{v} = m \int \vec{v} \cdot d\vec{v}$$



$$|\vec{v}| = v = (\vec{v} \cdot \vec{v})^{\frac{1}{2}}$$

$$\vec{v} \cdot d\vec{v} = |\vec{v}| \underbrace{|d\vec{v}| \cos \varphi}_{dv} = v dv$$

$$|d\vec{v}| \neq d(|\vec{v}|) = dv$$

$$d(\vec{v} \cdot \vec{v}) = d\vec{v} \cdot \vec{v} + \vec{v} \cdot d\vec{v} = 2\vec{v} \cdot d\vec{v},$$

$$\vec{v} \cdot d\vec{v} = \frac{1}{2} d(\vec{v} \cdot \vec{v}) = \frac{1}{2} d(v^2) = v dv$$

$$A = \int \vec{F} \cdot d\vec{r} = \int m \frac{d\vec{v}}{dt} \cdot \vec{v} dt = \int m d\vec{v} \cdot \vec{v} = m \int \vec{v} \cdot d\vec{v} = m \int v dv$$

$$A = m \int \vec{v} \cdot d\vec{v} = m \int_{v_1}^{v_2} v dv = \frac{1}{2} m v^2 \Big|_{v_1}^{v_2} = \frac{1}{2} m v_2^2 - \frac{1}{2} m v_1^2 .$$

kinetična energija **točkastega** telesa:

$$W_k = \frac{1}{2} m v^2$$

$$A = \int \vec{F} \cdot d\vec{s} = \Delta W_k$$

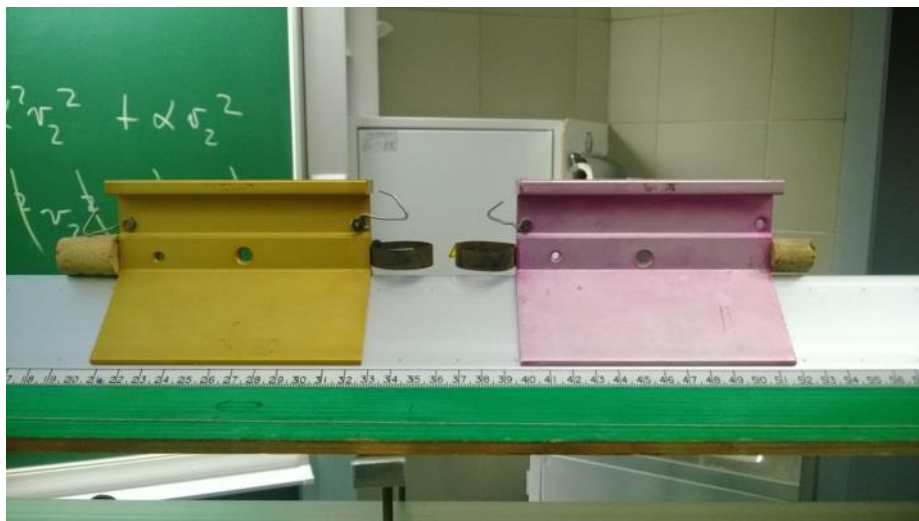
**TOGO telo**, ki se giblje po premici (premo gibanje) :

$$W_k = \frac{1}{2} m v^2$$

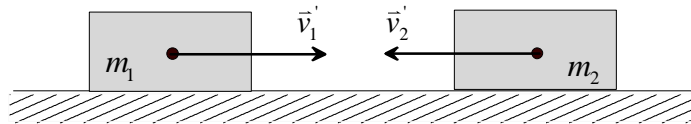
### Zakon o ohranitvi kinetične energije

$$0 = A = \int \vec{F} \cdot d\vec{s} = \Delta W_k \quad \Delta W_k = 0 \quad W_{k,zac} = W_{k,kon}$$

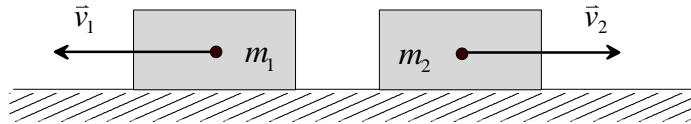
Zgled: **prožni (elastični) trk** dveh enako težkih jahačev (na zračni klopi)



pred trkom:



po trku:



$$m_1 \bar{v}_1' + m_2 \bar{v}_2' = m_1 \bar{v}_1 + m_2 \bar{v}_2$$

$$\frac{1}{2} m_1 v_1'^2 + \frac{1}{2} m_2 v_2'^2 = \frac{1}{2} m_1 v_1^2 + \frac{1}{2} m_2 v_2^2$$

poseben primer :  $v_2' = 0$ :

$$m_1 v_1' = m_1 v_1 + m_2 v_2 \qquad v_1' = v_1 + \left( \frac{m_2}{m_1} \right) v_2$$

$$\frac{1}{2} m_1 v_1'^2 = \frac{1}{2} m_1 v_1^2 + \frac{1}{2} m_2 v_2^2 \qquad v_1'^2 = v_1^2 + \left( \frac{m_2}{m_1} \right) v_2^2$$

(1)  $\Rightarrow v_1' = v_1 - \alpha v_2$     utamir  $v_2$  (2)  $\Rightarrow$   
 $v_1'^2 = (v_1 - \alpha v_2)^2 + \alpha v_2^2$   
 ~~$v_1'^2 = v_1^2 - 2v_1\alpha v_2 + \alpha^2 v_2^2 + \alpha v_2^2$~~   
 $2v_1' v_2 = \alpha v_2^2 + v_2^2$   
 $2v_1' = \alpha v_2 + v_2$   
 $v_2 = v_1' \frac{2}{1+\alpha}$

$v_1' = v_1 - \alpha v_1' \frac{2}{1+\alpha} = \frac{v_1 + \alpha v_1' - 2\alpha v_1'}{1+\alpha} = v_1' \frac{1-\alpha}{1+\alpha}$   
 $v_1' = v_1 \frac{1-\alpha}{1+\alpha}$

$$v_1 = \frac{v_1' \left(1 - \frac{m_2}{m_1}\right)}{\left(1 + \frac{m_2}{m_1}\right)} \quad v_2 = \frac{2v_1'}{1 + \frac{m_2}{m_1}}$$

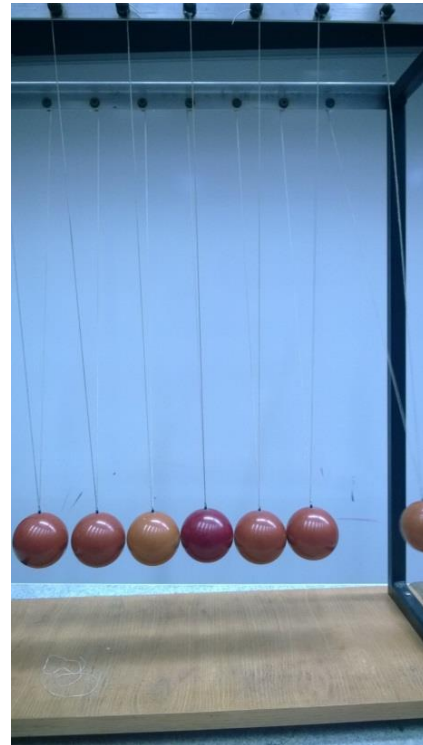
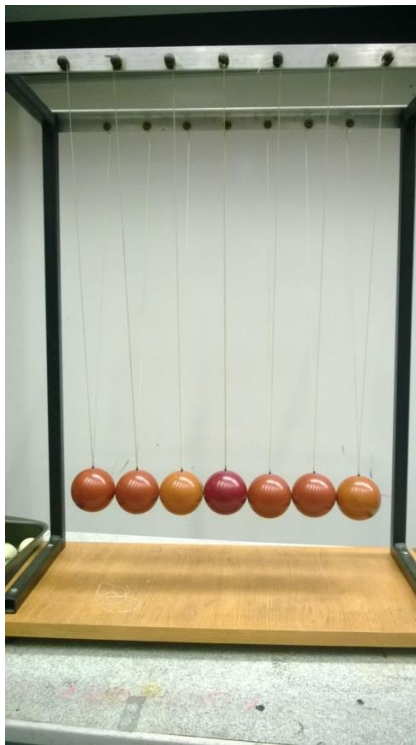
$$m_1 = m_2$$

:

$$v_1 = 0$$

$$v_2 = v_1'$$

**Zgled:** biljarde krogle



Elastični in neelastični trki:

<https://www.youtube.com/watch?v=jRliH0jVilM>

<https://www.youtube.com/watch?v=51IFubnEAsU>

Biljardne krogle (elastični trki):

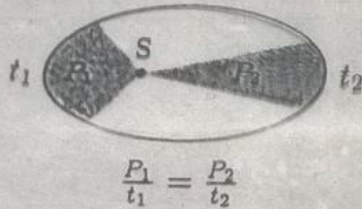
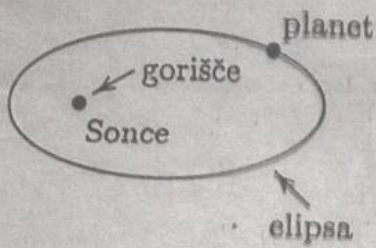
<https://www.youtube.com/watch?v=ofgeRSCLyXc>

# GRAVITACIJA

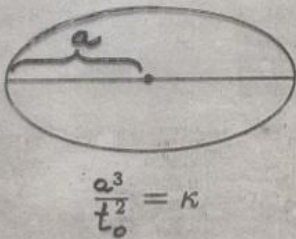


## KEPLERJEVI ZAKONI

Johannes Kepler  
(1571-1630)



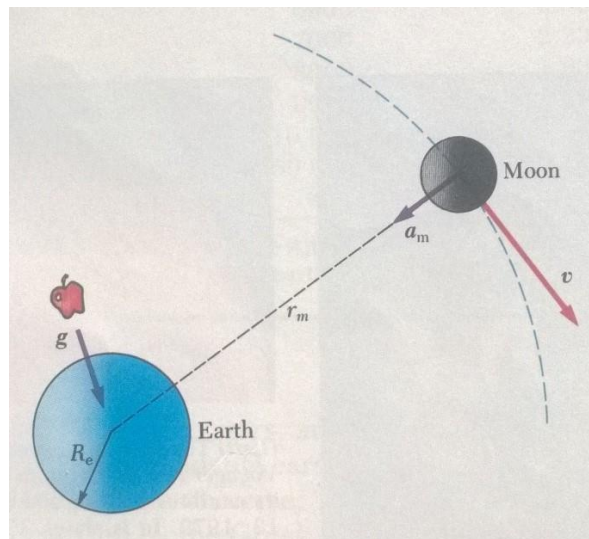
$t \equiv \text{čas}$



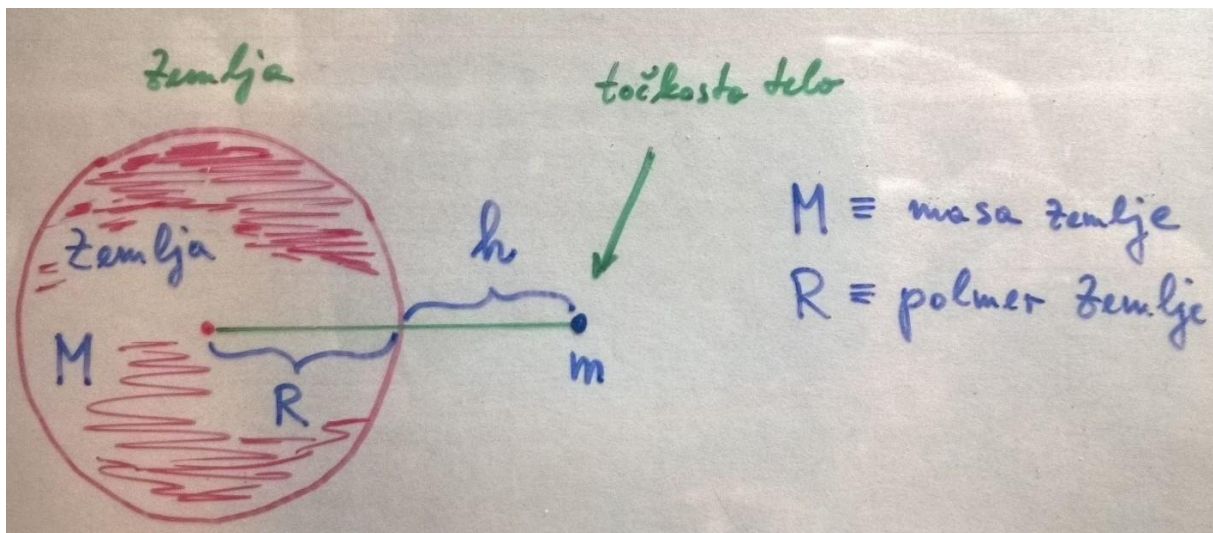
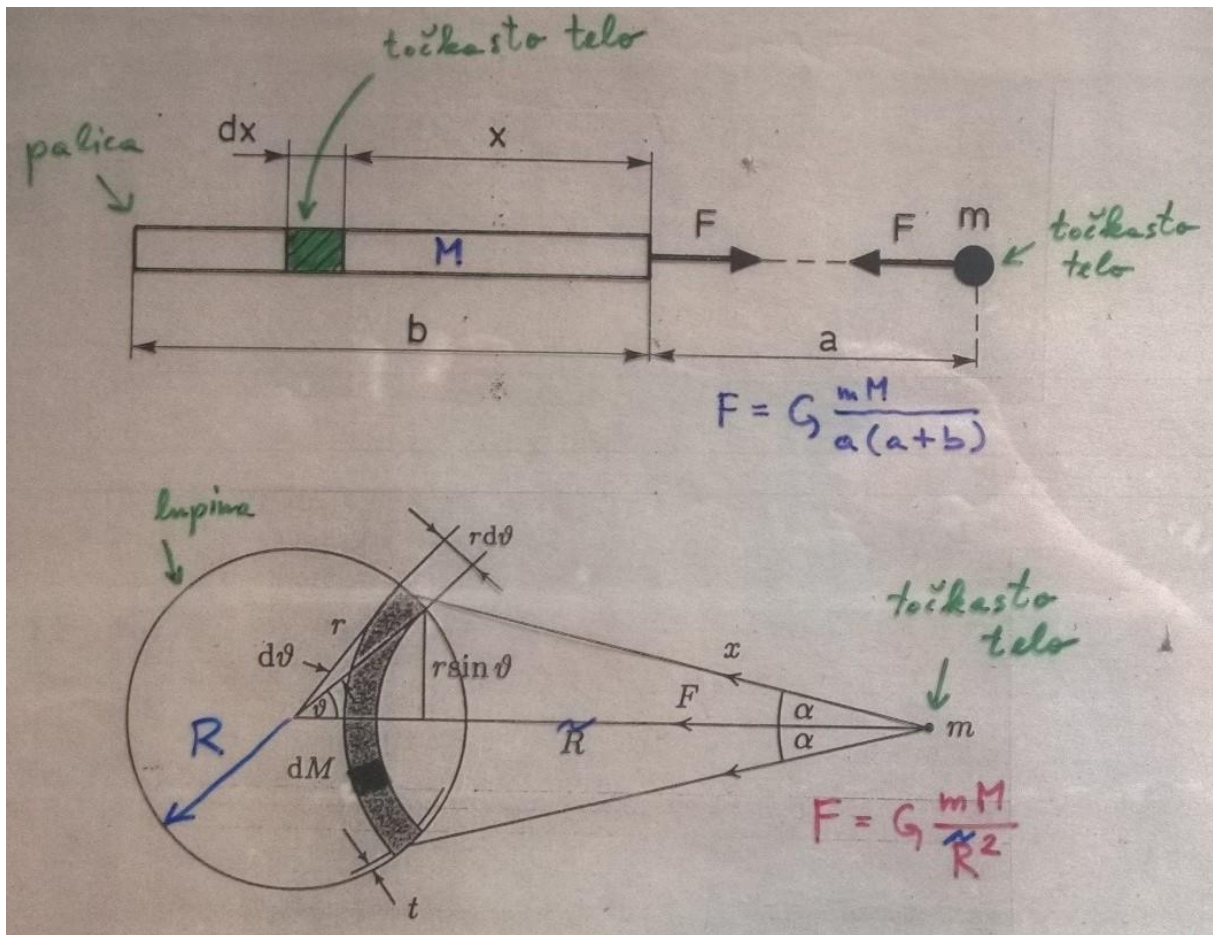
Planet	$r$ [UA]	$t_o$ [letr]	$\frac{r^3}{t_o^2}$ [ $\frac{UA^3}{letr^2}$ ]
Merkur	0,387	0,241	0,998
Venera	0,723	0,616	0,996
Zemlja	<u>1,000</u>	<u>1,000</u>	<u>1,000</u>
Mars	1,524	1,88	1,001
Saturn	5,20	11,86	1,000
Jupiter	9,54	29,46	1,000
Uran	19,18	84,0	1,001
Neptun	30,06	164,8	1,001
Pluton	39,5	247,7	1,001



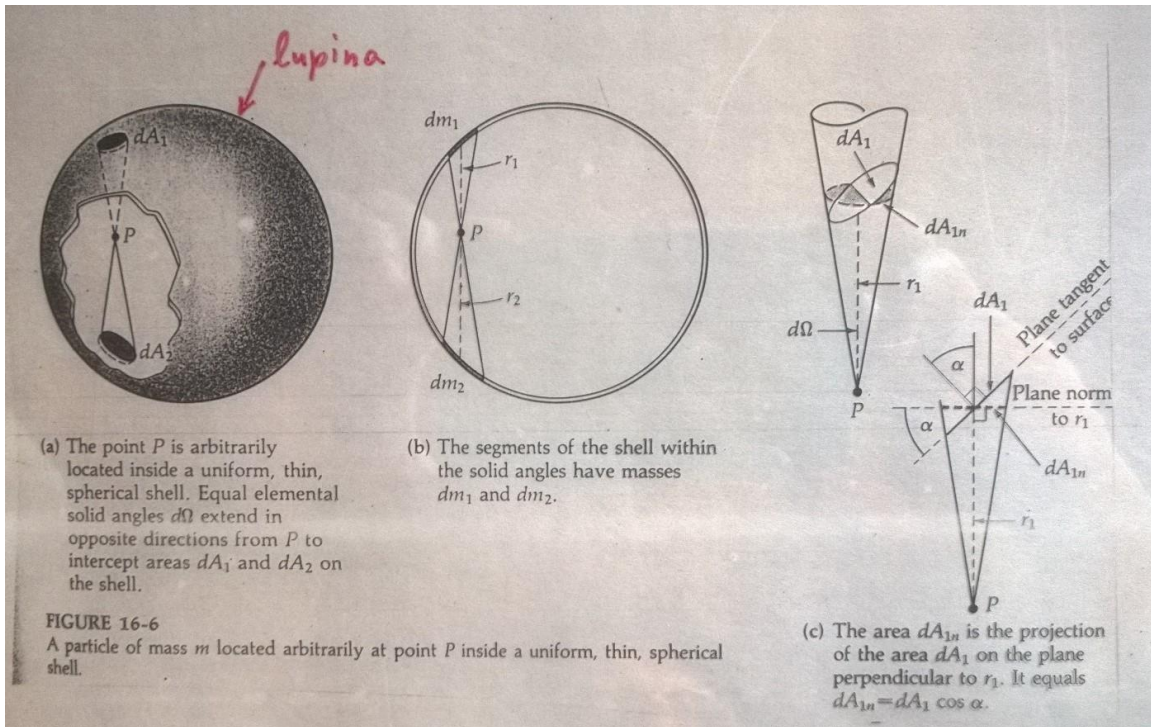
## Newtonov gravitacijski zakon



$$\vec{F}_{1,2} = G \frac{m_1 m_2}{r^2}$$



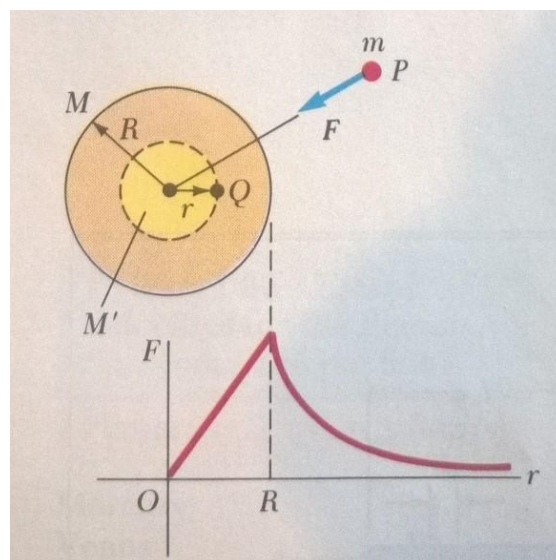
$$\vec{F}_g = -G \frac{mM_z}{r^2} \frac{\vec{r}}{r}$$



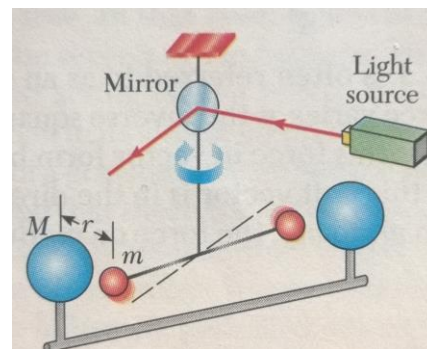
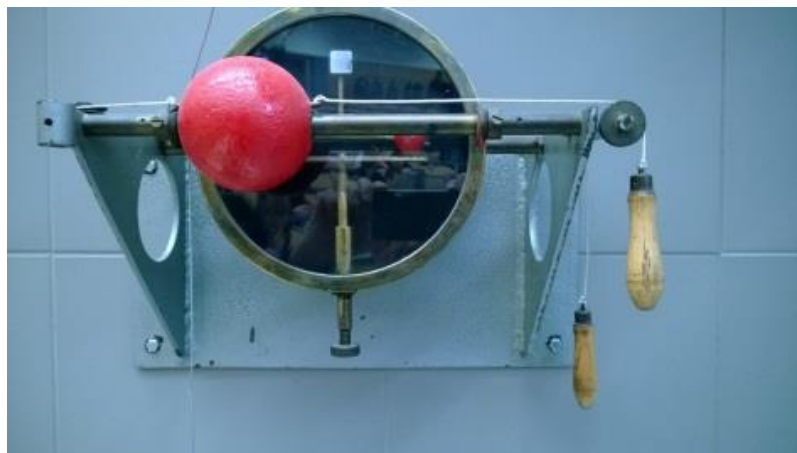
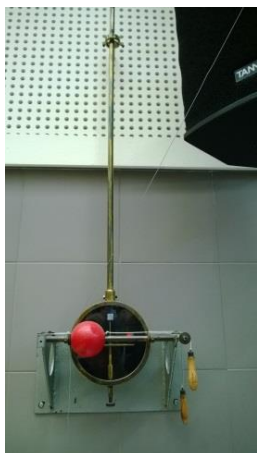
$$dm_1 = \sigma dA_1 = \frac{\sigma d\Omega r_1^2}{\cos \alpha} \quad \text{and} \quad dm_2 = \sigma dA_2 = \frac{\sigma d\Omega r_2^2}{\cos \alpha}$$

These two elements of mass exert gravitational forces on the particle  $m$ . The two forces are in opposite directions, and the ratio of their magnitudes is

$$\frac{dF_1}{dF_2} = \frac{\left(\frac{Gm dm_1}{r_1^2}\right)}{\left(\frac{Gm dm_2}{r_2^2}\right)} = \frac{\left(\frac{\sigma d\Omega r_1^2}{\cos \alpha r_1^2}\right)}{\left(\frac{\sigma d\Omega r_2^2}{\cos \alpha r_2^2}\right)} = 1$$



# MERJENJE GRAVITACIJSKE KONSTANTE IN POSPEŠKA (Cavendishova gravitacijska tehnica)

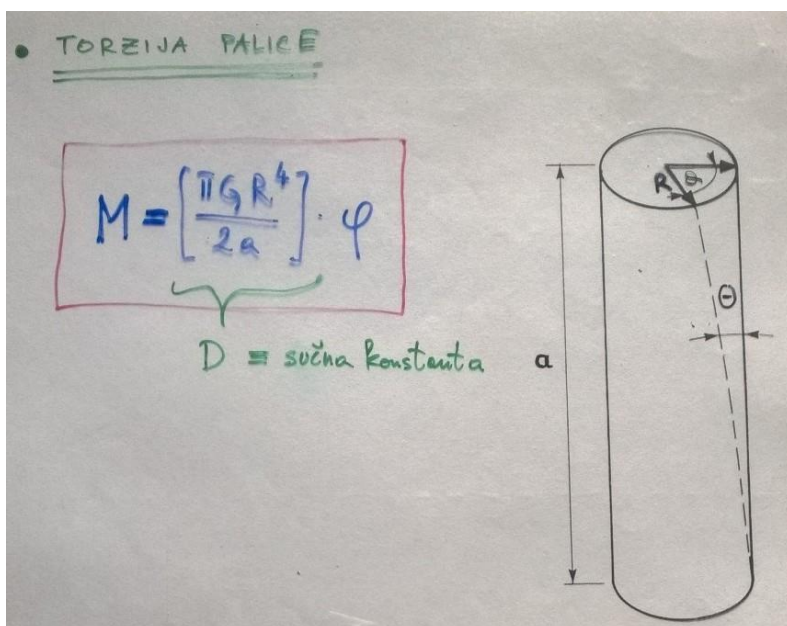


Cavendishova tehnica

Lord Cavendish  
l. 1798 izmeril  
gravitacijsko konstanto  $G$

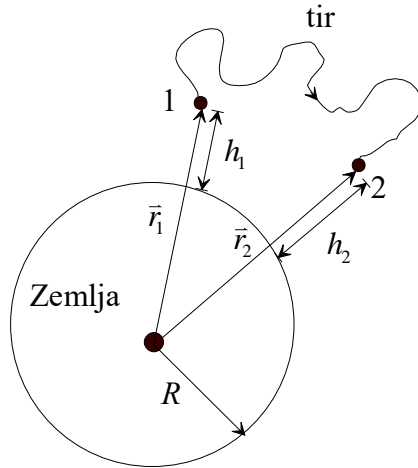
$G = 6.67 \cdot 10^{-11} \text{ Nm}^2/\text{kg}^2$

## Torzijska tehnica na žico (torzija kovinske tanke palice)



## Gravitacijska potencialna energija

$$\vec{F}_g = -G \frac{m M_z}{r^2} \frac{\vec{r}}{r}$$



R = polmer Zemlje  
h = nadmorska višina

$$\vec{F} = \vec{F}_{ost} + \vec{F}_g$$

$$A = \int (\vec{F}_{ost} + \vec{F}_g) \cdot d\vec{s} = \int (\vec{F}_{ost} + \vec{F}_g) \cdot d\vec{r} = \Delta W_k$$

$$A_{ost} = \int \vec{F}_{ost} \cdot d\vec{r} = \Delta W_k - \int \vec{F}_g \cdot d\vec{r}$$

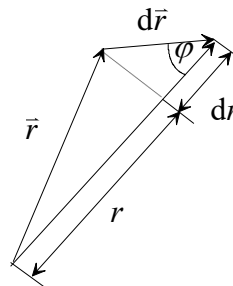
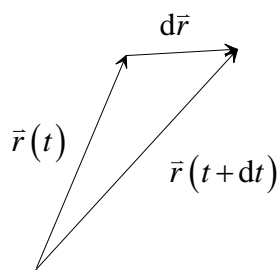
$$\begin{aligned} - \int \vec{F}_g \cdot d\vec{r} &= \int G \frac{m M_z}{r^2} \frac{\vec{r}}{r} \cdot d\vec{r} = G m M_z \int \frac{1}{r^3} \vec{r} \cdot d\vec{r} = \\ &= G m M_z \int \frac{1}{r^3} r dr = G m M_z \int_{r_1}^{r_2} \frac{dr}{r^2} = G m M_z \left( -\frac{1}{r} \right) \Big|_{r_1}^{r_2} = \\ &= -G \frac{m M_z}{r} \Big|_{r_1}^{r_2} = -G \frac{m M_z}{r_2} - \left( -G \frac{m M_z}{r_1} \right) = \Delta W_p \end{aligned}$$

$$\boxed{W_p = -G \frac{m M_z}{r}} \quad \Delta W_p = W_{p,2} - W_{p,1}$$

$$A_{ost} = \int \vec{F}_{ost} \cdot d\vec{r} = \Delta W_k - \int \vec{F}_g \cdot d\vec{r}$$

$$\boxed{A_{ost} = \Delta W_k + \Delta W_p}$$

izrek o kinetični in potencialni energiji za **točkasto telo**



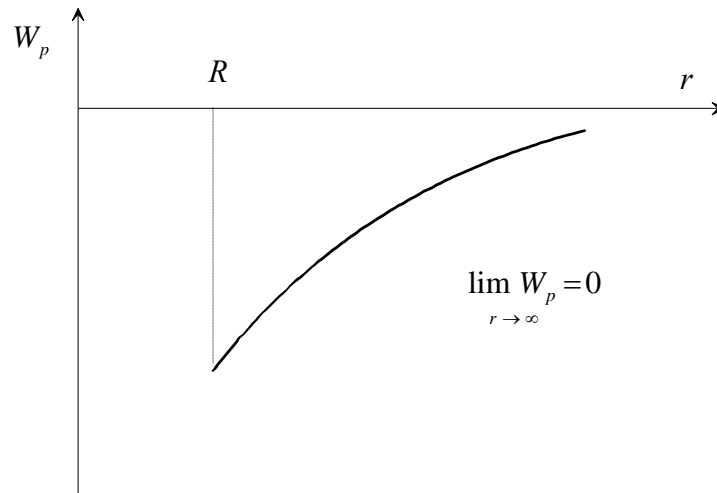
$$d(\vec{r} \cdot \vec{r}) = d\vec{r} \cdot \vec{r} + \vec{r} \cdot d\vec{r} = 2\vec{r} \cdot d\vec{r}$$

$$\vec{r} \cdot d\vec{r} = \frac{1}{2} d(\vec{r} \cdot \vec{r}) = \frac{1}{2} d(r^2) = r dr$$

$$W_p = -G \frac{m M_z}{r}$$

$$r = R + h$$

$$g_0 = G \frac{M_z}{R^2} \cong 9.8 \text{ ms}^{-2}$$



**majhne nadmorske višine  $h$  :**

$$W_p = -G \frac{mM_z}{r} = -G \frac{mM_z}{(R+h)} = -G \frac{mM_z}{R \left(1 + \frac{h}{R}\right)} = -G \frac{mM_z}{R} \left(1 - \frac{h}{R} + \frac{h^2}{R^2} - \dots\right)$$

$$\frac{h}{R} \rightarrow 0 \quad W_p \cong -G \frac{mM_z}{R} \left(1 - \frac{h}{R}\right) = -G \frac{mM_z}{R} + G \frac{M_z}{R^2} mh$$

$$g_0 = G \frac{M_z}{R^2} \cong 9.8 \text{ms}^{-2}$$

$$\boxed{W_p = m g_0 h}$$



## UBEŽNA HITROST (groba ocena)

$$A_{\text{odt}} = 0 = \Delta W_p + \Delta W_k$$

$$\Delta(W_p + W_k) = 0 \Rightarrow W_p + W_k = \text{konst.}$$

$$(W_p + W_k)_{t=R} = (W_p + W_k)_{t \rightarrow \infty}$$

$$-G \frac{mM}{R} + \frac{m v_0^2}{2} = 0 + 0$$

} ker pri  $t \rightarrow \infty$   
 $W_k \rightarrow 0$   
 $W_p \rightarrow 0$

$$\Downarrow$$

$$v_0 = \left( \frac{2GM}{R} \right)^{1/2} \approx \underline{11 \text{ km/s}}$$

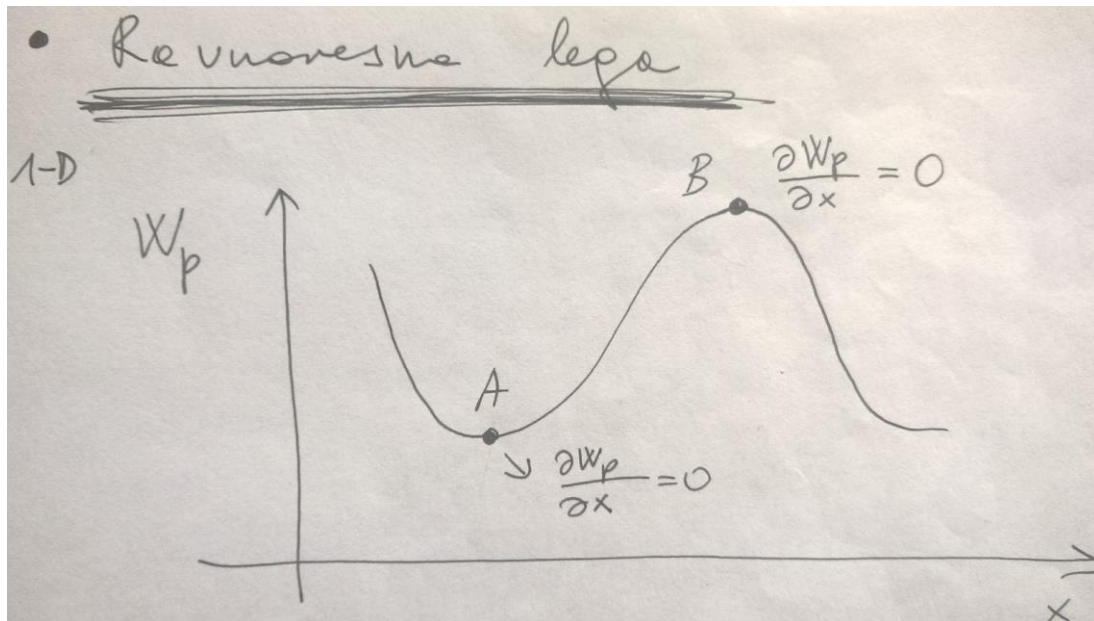

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$$\left( \frac{2GM}{R} \right)^{1/2} = \left( 2 \underbrace{\frac{GM}{R^2}}_{g_0} R \right)^{1/2} = (2g_0 R)^{1/2}$$

$R = 6400 \text{ km}$   
 $g_0 = 9.8 \text{ m s}^{-2}$

**TABLE 14.3** Escape Velocities for the Planets, the Moon, and the Sun

Planet	$v_{\text{esc}}$ (km/s)
Mercury	4.3
Venus	10.3
Earth	11.2
Moon	2.3
Mars	5.0
Jupiter	60
Saturn	36
Uranus	22
Neptune	24
Pluto	1.1
Sun	618



## DRUGE ENERGIJE : PROŽNOSTNA (ELASTIČNA) ENERGIJA



$F = kx$

$x = \text{razteženost vzmeti}$

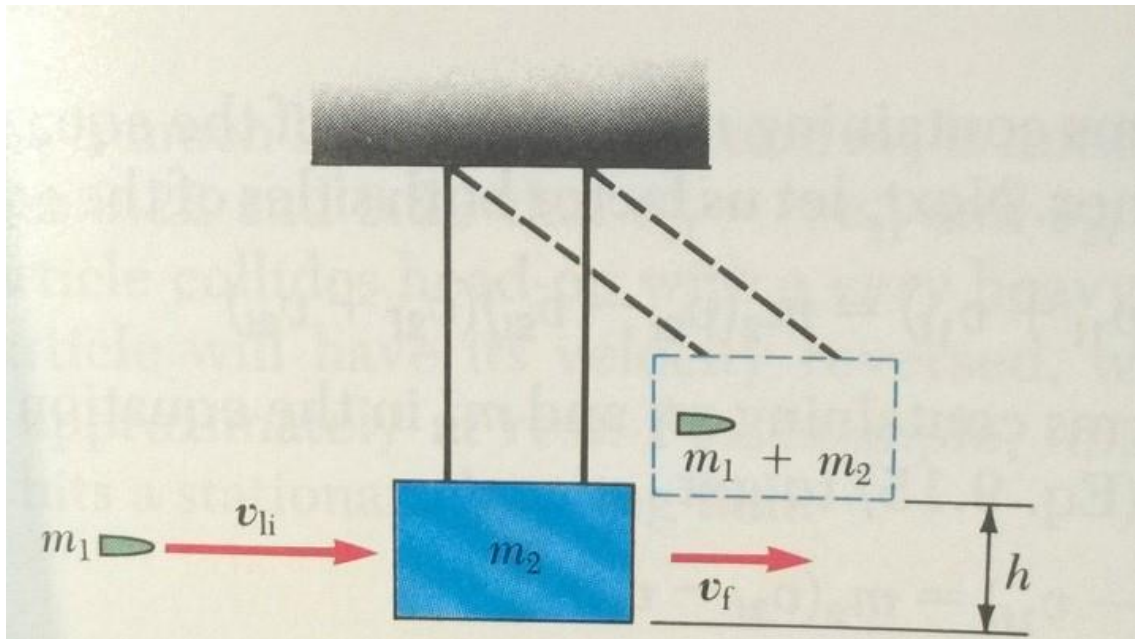
režec:  $x \rightarrow x+dx$

$dx \equiv \text{premišle}$

$$A = \int_{x_1}^{x_2} kx \, dx = \left. \frac{kx^2}{2} \right|_{x_1}^{x_2} = \frac{kx_2^2}{2} - \frac{kx_1^2}{2}$$

prožnostna energija viječne vzmeti:  $W = \frac{kx^2}{2}$

## ZGLED : balistično nihalo

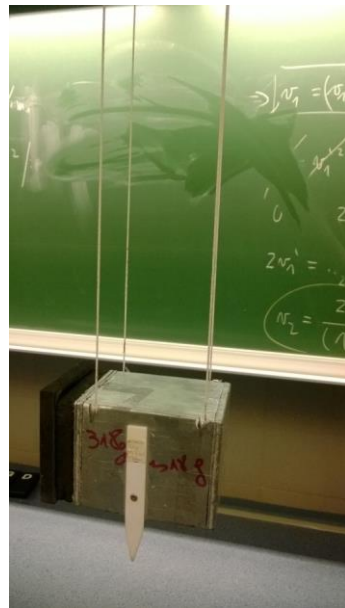
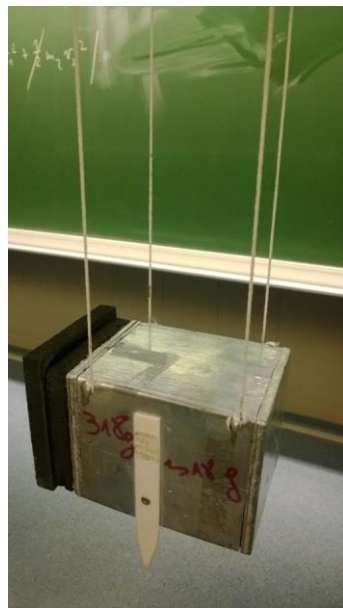
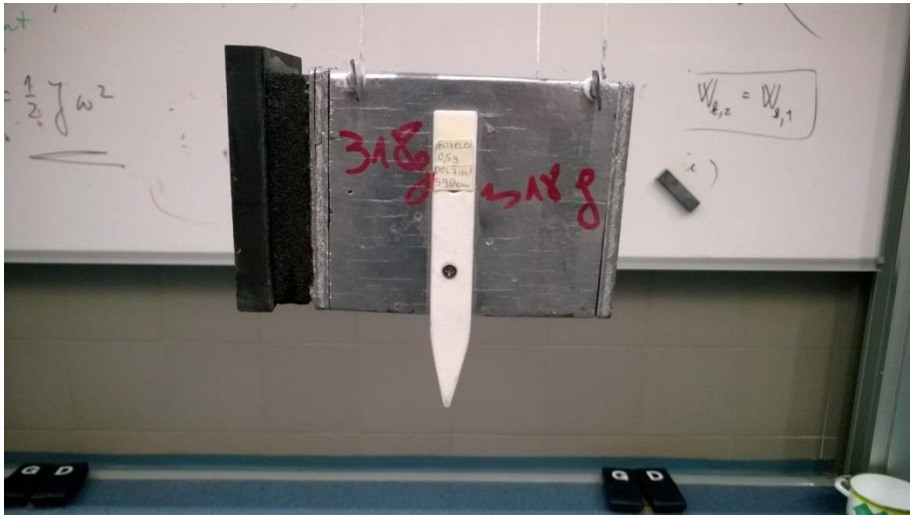


$$m_1 v_{li} = (m_1 + m_2) v_f \quad (\Delta G = 0)$$

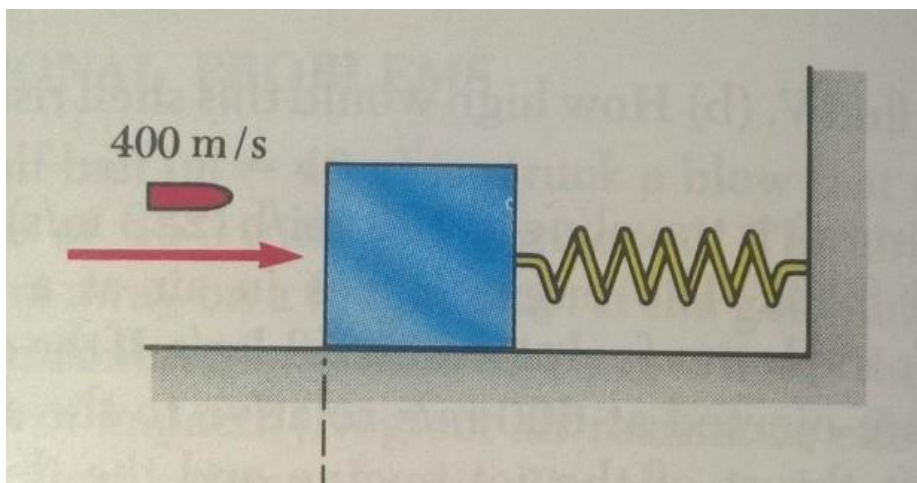
$$\left[ \frac{1}{2} (m_1 + m_2) v_f^2 = (m_1 + m_2) g_0 h \right.$$

$$\Rightarrow v_f = \sqrt{2 g_0 h}$$

$$v_{li} = \frac{(m_1 + m_2)}{m_1} v_f = \frac{(m_1 + m_2)}{m_1} \sqrt{2 g_0 h}$$



**ZGLED:** ne-elastičen trk, elastična energija



# MEHANSKO RAVNOVESJE

$$\sum_i \vec{F}_i = 0$$

$$\sum_i \vec{M}_i = 0$$

